



Mohsen Khadem

is hereby selected as a

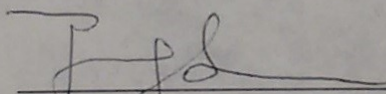
Student Best Paper Finalist
at the 2017 American Control Conference

for authoring and presenting the paper:

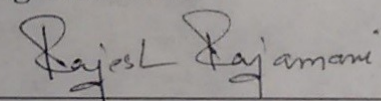
Mohsen Khadem (Student Author), Mahdi Tavakoli, & Carlos Rossa
University of Alberta

**Feedback-Linearization-based 3D Needle Steering in a Frenet-Serret Frame
Using a Reduced Order Bicycle Model**

On behalf of the 2017 ACC Organizing Committee



Jing Sun, General Chair



Rajesh Rajamani, Program Chair