



*The IEEE International Conference on Autonomous Systems*



# *Best Paper Award*

*Presented to*

*Amir Zakerimanesh, Tony Qiu and Mahdi Tavakoli*

*For their paper:*

*Heterogeneous Vehicular Platooning With Stable Decentralized Linear Feedback Control*

*IEEE Signal Processing Society, ICAS 2021  
Montreal, Quebec, Canada*

*Amir Asif  
General Chair*

*Arash Mohammadi  
General Chair*

*Saif alZahir  
Awards Chair*