

Kang, Bongsoo	Hannam Univ
Park, Edward J.	Simon Fraser Univ
16:50-17:10, Paper WeCT1.5	Add to My Program <input type="checkbox"/>
<i>Design and Shape Control of a Three-Section Continuum Robot</i>	
Ouyang, Bo	City Univ. of Hong Kong
Liu, Yunhui	Chinese Univ. of Hong Kong
Sun, Dong	City Univ. of Hong Kong
17:10-17:30, Paper WeCT1.6	Add to My Program <input type="checkbox"/>
<i>Motion Control of Articulated Rigid Bodies Used to Model Deformable Biomaterials</i>	
Hu, Ai-Ping	Georgia Tech. Res. Inst
Harvey, Noah	Georgia Tech. Res. Inst
Washington, Clarence	Georgia Inst. of Tech
WeCT2 Invited Session, KC Husky Great Hall Room 103	Add to My Program <input type="checkbox"/>
<i>Control Issues in Mechatronic Systems for Medicine</i>	
Chair: Patel, Rajnikant V.	The Univ. of Western Ontario
Co-Chair: Herzig, Nicolas	Ampere UMR CNRS 5005 - INSA Lyon - Univ. De Lyon
Organizer: Rossa, Carlos	Univ. of Alberta
Organizer: Tavakoli, Mahdi	Univ. of Alberta
15:30-15:50, Paper WeCT2.1	Add to My Program <input type="checkbox"/>
<i>Stiffness Control of Pneumatic Actuators to Simulate Human Tissues Behavior on Medical Haptic Simulators (I)</i>	
Herzig, Nicolas	Ampere UMR CNRS 5005 - INSA Lyon - Univ. De Lyon
Moreau, Richard	INSA-Lyon
Lelevé, Arnaud	INSA De Lyon (Inst. National Des Sciences Appliquees), Univ
Pham, Minh Tu	INSA De Lyon (Inst. National Des Sciences Appliquees)
15:50-16:10, Paper WeCT2.2	Add to My Program <input type="checkbox"/>
<i>Tendon-Sheath Analysis for Modeling and Control of Steerable Ablation Catheters (I)</i>	
Khoshnam Tehrani, Mahta	The Univ. of Western Ontario
Patel, Rainikant V.	The Univ. of Western Ontario
16:10-16:30, Paper WeCT2.3	Add to My Program <input type="checkbox"/>
<i>An Integrator-Backstepping Control Approach for Out-Of-Plane Needle Deflection Minimization (I)</i>	
Waine, Michael	Univ. of Alberta
Rossa, Carlos	Univ. of Alberta
Usmani, Nawaid	Cross Cancer Inst
Sloboda, Ronald	Cross Cancer Inst
Tavakoli, Mahdi	Univ. of Alberta
16:30-16:50, Paper WeCT2.4	Add to My Program <input type="checkbox"/>
<i>Partial Estimation of Needle Tip Orientation in Generalized Coordinates in Ultrasound Image-Guided Needle Insertion (I)</i>	
Fallahi, Bitā	Univ. of Alberta
Rossa, Carlos	Univ. of Alberta
Sloboda, Ronald	Cross Cancer Inst
Usmani, Nawaid	Cross Cancer Inst
Tavakoli, Mahdi	Univ. of Alberta
16:50-17:10, Paper WeCT2.5	Add to My Program <input type="checkbox"/>
<i>Simple Torso Model for Upper Limb Compensatory Assessment after Stroke</i>	
Nordin, Nurdiana	Univ. of Auckland
Xie, Shane	Univ. of Auckland
Wuensche, Burkhard	Univ. of Auckland
WeCT3 Regular Session, KC Husky Great Hall Room 105	Add to My Program <input type="checkbox"/>