

Superimposed Pilot Based Joint CFO and Channel Estimation for CP-OFDM Modulated Two-Way Relay Networks

Gongpu Wang[†], Feifei Gao[‡], and Chintha Tellambura[†]

[†]University of Alberta, Edmonton, Canada,

[‡]Jacobs University, Bremen, Germany

Email: gongpu@ece.ualberta.ca

Outline

- Introduction
- Problem Formulation
- Proposed Solution
- Simulation Results
- Conclusion

Introduction

- Two-way transmission was firstly exploited by Shannon [Shannon, 1961].
- Two-way relay networks (TWRN) now has drawn much attention due to its improved spectral efficiency over one-way relay networks (OWRN).
- The overall communication rate between two source terminals in TWRN is approximately twice that achieved in OWRN [Rankov, 2006].

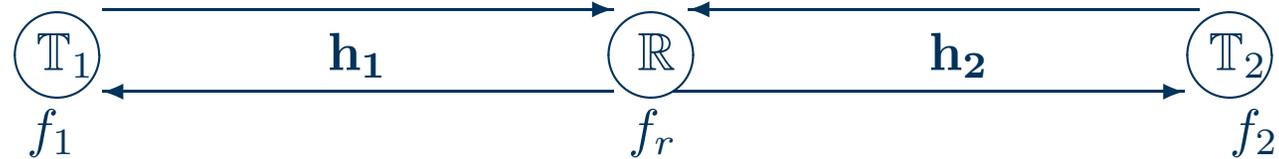


Figure 1: System configuration for two-way relay network.

Introduction

- Most existing works in TWRN assumed perfect synchronization and channel state information (CSI).
- Channel estimation problems in amplify-and-forward (AF) TWRN are different from those in traditional communication systems.
- Flat-fading [Gao, 2009, TCOM] and frequency-selective [Gao, 2009, TSP] channel estimation and training design for AF TWRN.
- Joint frequency offset (CFO) and channel estimation: modeling [Wang, 2009, Globecom]; CP-OFDM [Wang, 2010, ICC]; ZP-OFDM [Wang, 2010, WCNC].

Problem Formulation

- However, only the convoluted channel parameters \mathbf{a} and \mathbf{b} , and the mixed CFO value v can be found in the previous works.

$$w = f_r - f_1, \quad \mathbf{a} = (\boldsymbol{\Omega}^{(L+1)}[-w]\mathbf{h}_1) \otimes \mathbf{h}_1,$$
$$v = f_2 - f_1, \quad \mathbf{b} = (\boldsymbol{\Omega}^{(L+1)}[v - w]\mathbf{h}_1) \otimes \mathbf{h}_2.$$

- The individual frequency and channel parameters remain unknown to the source nodes.
- How to estimate individual frequency f_r, f_1, f_2 and channel parameters \mathbf{h}_1 and \mathbf{h}_2 ?

Proposed Solution

- Problem: How to obtain h_1 , h_2 and $w = f_r - f_1$?
- Our solution: superimposed pilots + iterative algorithms.

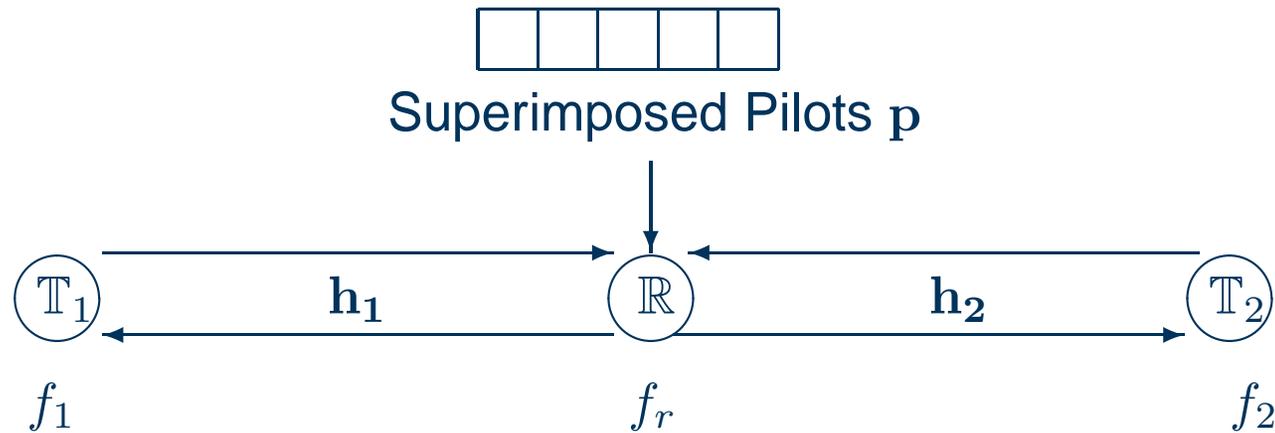


Figure 2: Two-way relay network with superimposed pilots at the relay node.

Superimposed Pilot Aided Estimation

- For CP-OFDM, the terminal node \mathbb{T}_1 will receive

$$\begin{aligned} \mathbf{y} &= \alpha \mathbf{H}_{cp}^{(N)} [\mathbf{a}] \mathbf{s}_1 + \alpha \mathbf{\Gamma}_L^{(N)} [v] \mathbf{H}_{cp}^{(N)} [\mathbf{b}] \mathbf{s}_2 + \mathbf{\Gamma}_L^{(N)} [w] \mathbf{H}_{cp}^{(N)} [\mathbf{h}_1] \mathbf{p}_0 + \mathbf{n}_e \\ &= \alpha \mathbf{S}_1 \mathbf{a} + \alpha \mathbf{\Gamma}_L^{(N)} [v] \mathbf{S}_2 \mathbf{b} + \mathbf{\Gamma}_L^{(N)} [w] \mathbf{P} \mathbf{h}_1 + \mathbf{n}_e. \end{aligned} \quad (1)$$

where \mathbf{S}_j is the $N \times (2L + 1)$ circulant matrix with the first column \mathbf{s}_j , and \mathbf{P} is the $N \times (L + 1)$ circulant matrix with the first column \mathbf{p}_0 .

- \mathbf{h}_1 , \mathbf{h}_2 , v and w to be estimated.
- Iteration to further refine our estimates

$$\begin{aligned} [v^{(1)}, w^{(1)}] &= \arg \min_{v, w} (\mathbf{y} - \alpha \mathbf{S}_1 \mathbf{a}^{(0)} - \alpha \mathbf{\Gamma}[v] \mathbf{S}_2 \mathbf{b}^{(0)} - \mathbf{\Gamma}[w] \mathbf{P} \mathbf{h}_1^{(0)})^H \\ &\quad \times \mathbf{R}^{-1} (\mathbf{y} - \alpha \mathbf{S}_1 \mathbf{a}^{(0)} - \alpha \mathbf{\Gamma}[v] \mathbf{S}_2 \mathbf{b}^{(0)} - \mathbf{\Gamma}[w] \mathbf{P} \mathbf{h}_1^{(0)}), \end{aligned}$$

where \mathbf{R} is the covariance matrix of \mathbf{n}_e .

Minimum Pilot Length

- Define \mathcal{K}_1 , \mathcal{K}_2 , and \mathcal{K}_r as the frequency domain pilot index sets from \mathbb{T}_1 , \mathbb{T}_2 , and \mathbb{R} , with cardinality K_1 , K_2 , and K_r respectively.
- We require $K_1 \geq L + 1$, $K_2 \geq L + 1$, $K_r \geq L + 1$ and $\mathcal{K}_1 \cup \mathcal{K}_2 \cup \mathcal{K}_r = \{1, \dots, N\}$.
- Since \mathbf{S}_j and \mathbf{P} are columnwise circulant matrices, they can be represented as

$$\mathbf{S}_j = \mathbf{F}^H \text{diag}\{\tilde{\mathbf{s}}_j\} \mathbf{F}_{[:,1:2L+1]} = \mathbf{F}_{[:,\mathcal{K}_j]}^H \text{diag}\{\check{\mathbf{s}}_j\} \mathbf{F}_{[\mathcal{K}_j,1:2L+1]} \quad (2)$$

$$\mathbf{P} = \mathbf{F}^H \text{diag}\{\tilde{\mathbf{p}}_0\} \mathbf{F}_{[:,1:L+1]} = \mathbf{F}_{[:,\mathcal{K}_r]}^H \text{diag}\{\check{\mathbf{p}}_0\} \mathbf{F}_{[\mathcal{K}_r,1:L+1]}. \quad (3)$$

Minimum Pilot Length (continued)

- Define $\bar{\mathcal{K}}_1$ as the complement set of \mathcal{K}_1 . Multiplying both sides with $\mathbf{F}_{[\bar{\mathcal{K}}_1, :]}$ yields

$$\mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{y} = \underbrace{\left[\alpha \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{\Gamma}[v] \mathbf{F}_{[:, \mathcal{K}_2]}^H \text{diag}\{\check{\mathbf{s}}_2\} \right]}_{\mathbf{C}_1} \underbrace{\left[\mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{\Gamma}[w] \mathbf{P} \right]}_{\mathbf{d}_1} \underbrace{\begin{bmatrix} \check{\mathbf{b}} \\ \mathbf{h}_1 \end{bmatrix}}_{\mathbf{d}_1} + \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{n}_e, \quad (4)$$

where $\check{\mathbf{b}} = \mathbf{F}_{[\mathcal{K}_2, 1:2L+1]} \mathbf{b}$ is the DFT response of \mathbf{b} on the subcarrier set \mathcal{K}_2 and \mathbf{C}_1 is an $(N - K_1) \times (K_2 + L + 1)$ matrix.

- Two-dimensional search estimator:

$$\{\hat{v}, \hat{w}\} = \arg \max_{v, w} \mathbf{y}^H \mathbf{F}_{[\bar{\mathcal{K}}_1, :]}^H \mathbf{C}_1 (\mathbf{C}_1^H \mathbf{C}_1)^{-1} \mathbf{C}_1^H \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{y}. \quad (5)$$

$$\hat{\mathbf{d}}_1 = (\mathbf{C}_1^H \mathbf{C}_1)^{-1} \mathbf{C}_1^H \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{y}. \quad (6)$$

Minimum Pilot Length (continued)

- Note that

$$\check{\mathbf{b}} = \mathbf{F}_{[\mathcal{K}_2, 1:2L+1]} \mathbf{H}_{zp}^{(L+1)} [\boldsymbol{\Omega}^{(L+1)} [v - w] \mathbf{h}_1] \mathbf{h}_2. \quad (7)$$

- Then, \mathbf{h}_2 can be estimated as

$$\hat{\mathbf{h}}_2 = (\mathbf{F}_{[\mathcal{K}_2, 1:2L+1]} \mathbf{H}_{zp}^{(L+1)} [\boldsymbol{\Omega}^{(L+1)} [v - w] \mathbf{h}_1])^\dagger \check{\mathbf{b}}. \quad (8)$$

- Iteration can be applied to further improve the estimation performance.
- The minimum number of N is $3L + 5$, when sets are disjoint and $K_1 = K_2 = L + 1$, $K_r = L + 3$.

A Special Case

- In practical applications, the relay terminal is often a simple device while the two source terminals may employ high-precision synchronization circuits.
- Thus, it is reasonable to expect the CFO between the two source terminals to be negligible.
- Then we can obtain

$$\begin{aligned}
 \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{y} = & \underbrace{\alpha \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \boldsymbol{\Gamma}[v] \mathbf{F}_{[:, \mathcal{K}_2]}^H}_{\approx 0} \text{diag}\{\check{s}_2\} \mathbf{F}_{[\mathcal{K}_i, 1:2L+1]} \mathbf{b} \\
 & + \underbrace{\mathbf{G}_{[\bar{\mathcal{K}}_1, :]} \boldsymbol{\Gamma}[w] \mathbf{P} \mathbf{h}_1}_{\mathbf{C}_2} + \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{n}_e, \quad (9)
 \end{aligned}$$

- CFO w can be estimated as

$$\hat{w} = \arg \max_w \mathbf{y}^H \mathbf{F}_{[\bar{\mathcal{K}}_1, :]}^H \mathbf{C}_2 (\mathbf{C}_2^H \mathbf{C}_2)^{-1} \mathbf{C}_2^H \mathbf{F}_{[\bar{\mathcal{K}}_1, :]} \mathbf{y}, \quad (10)$$

Simulation Results: Minimum Pilot Length Case

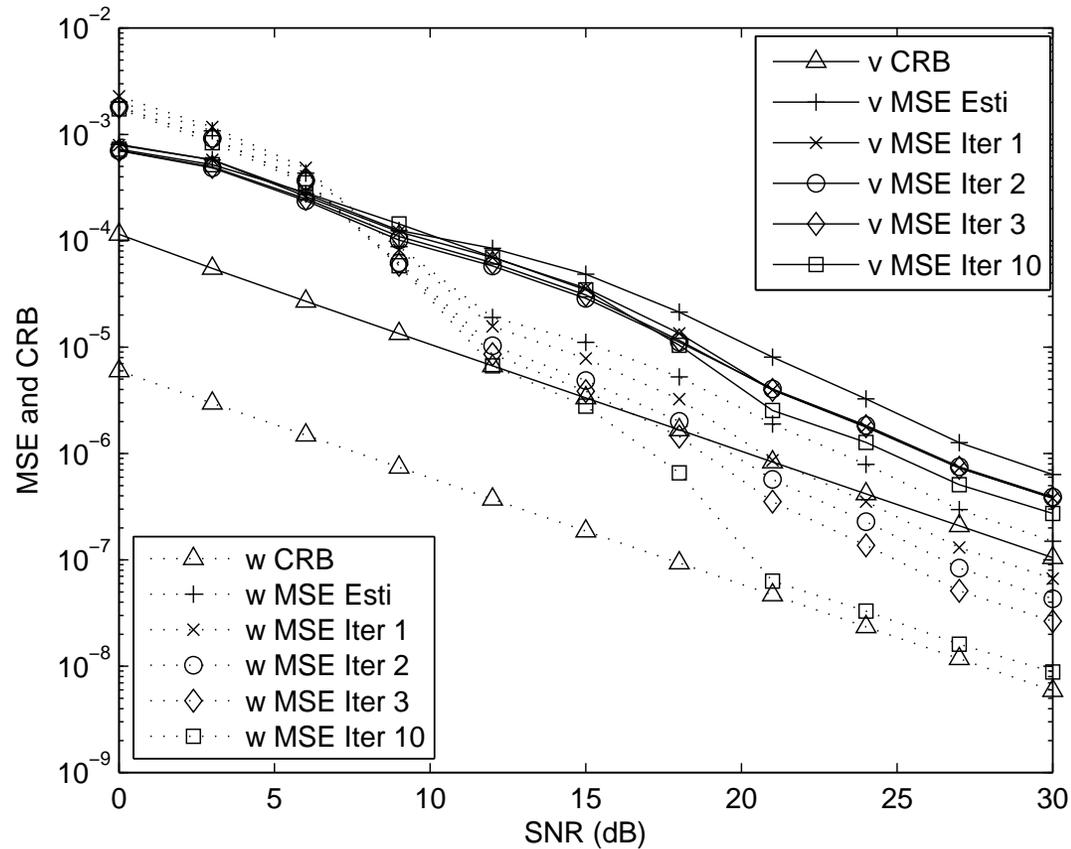


Figure 3: CFO estimation MSE versus SNR: $N = 14$

Simulation Results: Minimum Pilot Length Case

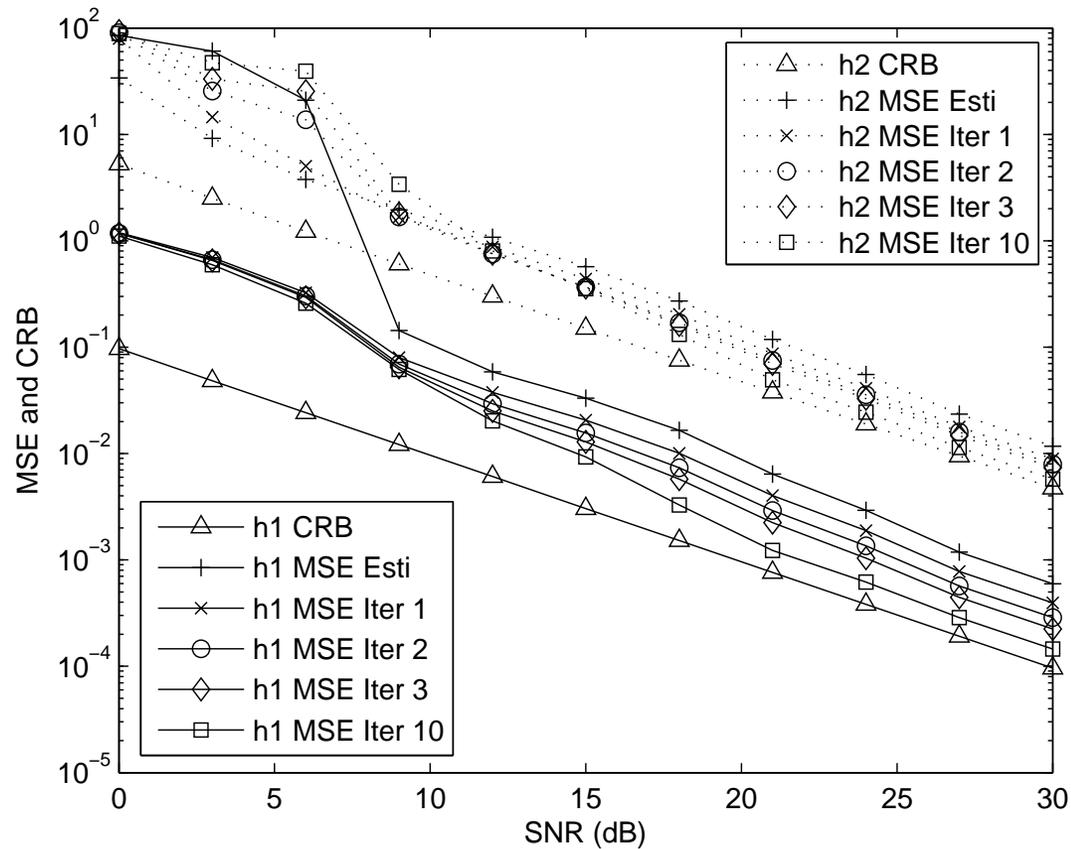


Figure 4: Channel estimation MSE versus SNR: $N = 14$

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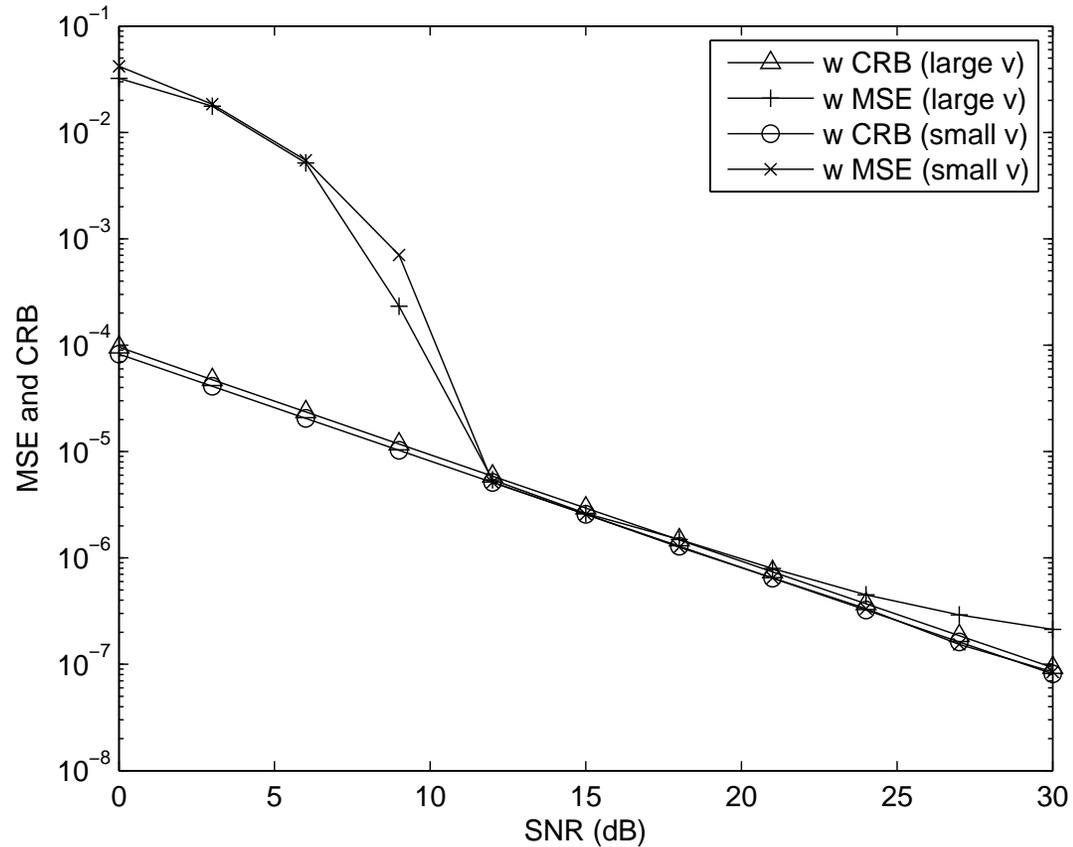


Figure 5: CFO estimation MSE versus SNR: $N = 9$

Simulation Results: A Special Case

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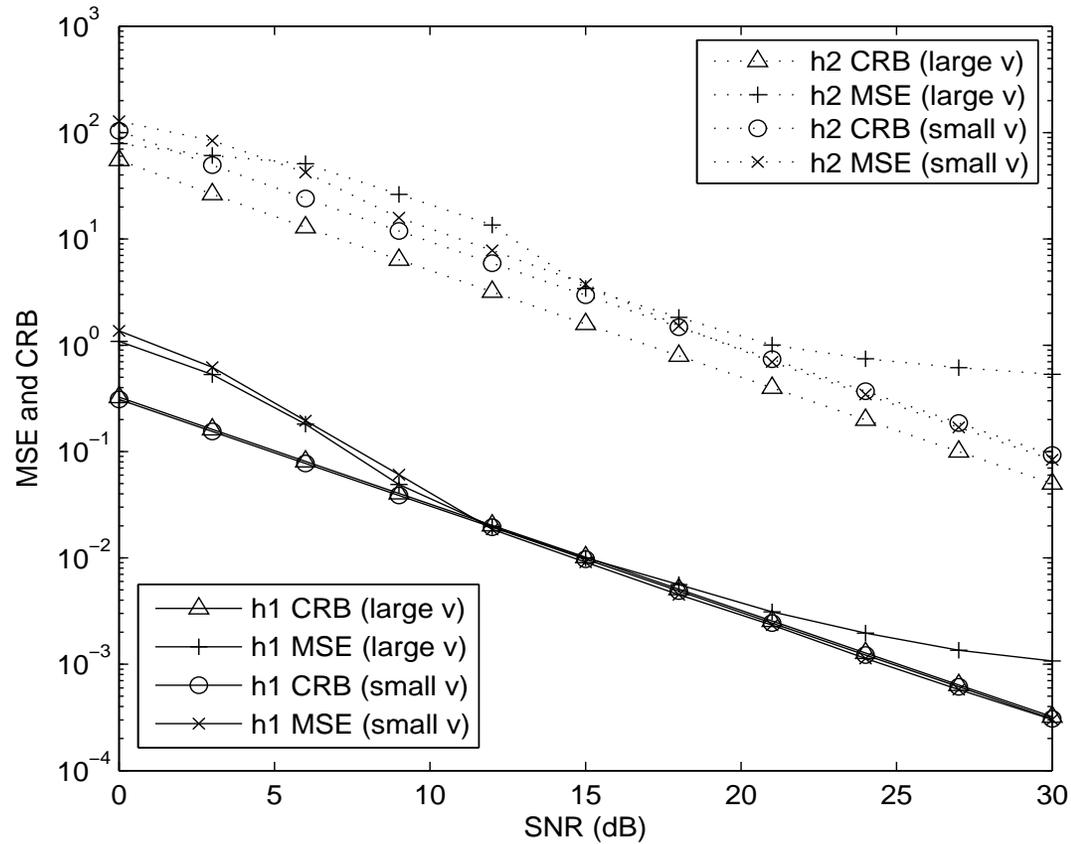


Figure 6: Channel estimation MSE versus SNR: $N = 9$

Conclusion

- Estimate individual channel parameters by introducing superimposed pilots at the relay node and using iterative algorithms.
- Less training is needed.
- Special case: small v .

Table 1: Comparison between adapted CP-OFDM and superimposed pilot aided CP-OFDM.

	Minimum Pilot Length	Estimated Parameters
adapted CP-OFDM	$4L + 3$	\mathbf{a} , \mathbf{b} and v
superimposed pilot	$3L + 5$	\mathbf{h}_1 , \mathbf{h}_2 , \mathbf{a} , \mathbf{b} , v and w

Questions and discussion?

Email: gongpu@ece.ualberta.ca