

Joint Frequency Offset and Channel Estimation Methods for Two-Way Relay Networks

Gongpu Wang[†], Feifei Gao* and Chintha Tellambura[†]

[†]Department of Electrical and Computer Engineering,
University of Alberta, Edmonton, Canada,

*School of Engineering and Science, Jacobs University, Bremen, Germany
Email: {gongpu}@ece.ualberta.ca

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Introduction

- Two-way relay networks (TWRN) can enhance the overall communication rate [Boris Rankov, 2006], [J.Ponniah, 2008].

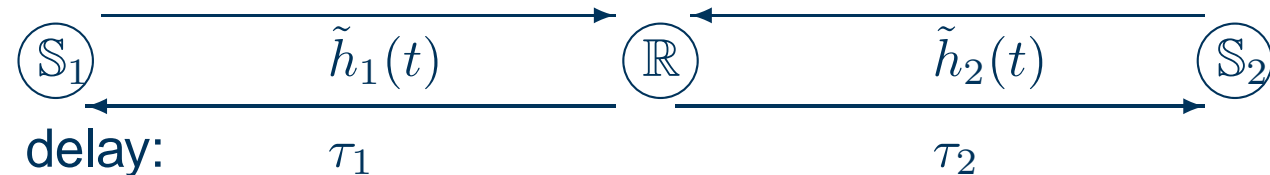


Figure 1: System configuration for two-way relay network.

Previous Results

- Most existing works in TWRN assumed perfect synchronization and channel state information (CSI).
- Channel estimation problems in amplify-and-forward (AF) TWRN are different from those in traditional communication systems.
- Flat-fading channel estimation and training design for AF TWRN has been done in [Feifei Gao, 2009].
- Our paper will focus on joint frequency offset (CFO) and channel estimation for AF TWRN.

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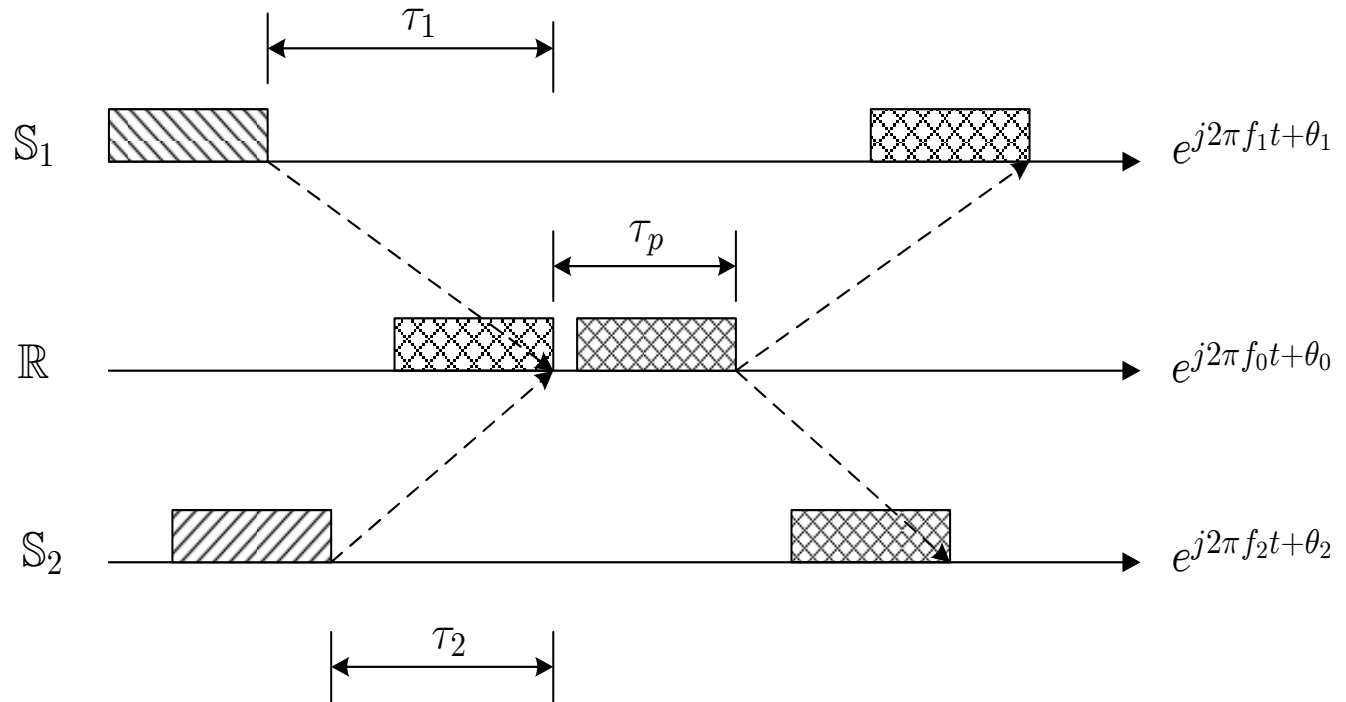


Figure 2: Illustration of channel delay and signal processing delay in two-way relay transmission.

Problem Formulation

- The passband signal sent by \mathbb{S}_i is

$$\tilde{s}_i(t) = \sum_{m=-\infty}^{+\infty} s_i[m]p(t - mT_s)e^{j2\pi f_i t}. \quad (1)$$

- The received signal in \mathbb{R} is

$$\tilde{r}_r(t) = \sum_{i=1}^2 \tilde{h}_i(t) * \tilde{s}_i(t) + \tilde{n}_r(t) \quad (2)$$

- The passband signal sent out by relay is then

$$\tilde{r}_s(t - \tau_p) = \alpha \sum_{i=1}^2 \tilde{h}_i(t) * \tilde{s}_i(t - \tau_p) + \alpha \tilde{n}_r(t - \tau_p) \quad (3)$$

Problem Formulation

- The data received at S_1 is

$$\begin{aligned}
 \tilde{y}(t) &= \tilde{h}_1(t) * \tilde{r}_s(t - \tau_p) + \tilde{n}_1(t), \\
 &= \alpha \sum_{i=1}^2 \left(((\tilde{h}_1(t) * \tilde{h}_i(t))e^{-j2\pi f_i t}) * s_i(t - \tau_p) \right) \\
 &\quad \times e^{j2\pi f_i(t - \tau_p)} + \alpha \tilde{h}_1(t) * \tilde{n}_r(t - \tau_p) + \tilde{n}_1(t). \quad (4)
 \end{aligned}$$

- Then S_1 down-convert $\tilde{y}(t)$ to baseband by $e^{-j2\pi f_1 t}$

$$\begin{aligned}
 y(t) &= \tilde{y}(t)e^{-j2\pi f_1 t} \\
 &= \alpha \left(\left((\tilde{h}_1(t) * \tilde{h}_1(t))e^{-j2\pi f_1 t} \right) * s_1(t - \tau_p) \right) e^{j\phi_1} \\
 &\quad + \alpha \left(\left((\tilde{h}_1(t) * \tilde{h}_2(t))e^{-j2\pi f_2 t} \right) * s_2(t - \tau_p) \right) e^{j2\pi f_2 t + j\phi_2} \\
 &\quad + \alpha \left(\tilde{h}_1(t) * \tilde{n}_r(t - \tau_p) \right) e^{-j2\pi f_1 t} + \tilde{n}_1(t)e^{-j2\pi f_1 t}. \quad (5)
 \end{aligned}$$

Problem Formulation

- The baseband signal is rewritten as

$$y(t) = a(t) * s_1(t - \tau_p) + b(t) * s_2(t - \tau_p)e^{j2\pi vt} + h_1(t) * (\tilde{n}_r(t - \tau_p)e^{-j2\pi f_1 t}) + \tilde{n}_1(t)e^{-j2\pi f_1 t}. \quad (6)$$

- Following the traditional approach [M.Morelli 2000], we can obtain

$$\mathbf{y} = \mathbf{S}_1 \mathbf{a} + \mathbf{\Gamma} \mathbf{S}_2 \mathbf{b} + \mathbf{H}_1 \mathbf{n}_r + \mathbf{n} \quad (7)$$

where

$$\mathbf{\Gamma} = \text{diag}\left(1, e^{j2\pi v T_s}, \dots, e^{j2\pi v (N-1) T_s}\right),$$

$$\mathbf{H}_1 = \alpha \begin{bmatrix} h_1[L] & \dots & h_1[0] & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & h_1[L] & \dots & h_1[0] \end{bmatrix}.$$

Estimation Methods

- Approximated ML Estimation
- Nulling Based LS Method

Approximated ML Estimation

- Maximizing the probability density function (pdf) of \mathbf{y} :

$$p(\mathbf{y}|\Theta) = \frac{1}{\pi^N \det(\mathbf{H}_1 \mathbf{H}_1^H + \mathbf{I})} \times \exp\{(\mathbf{y} - \mathbf{S}_1 \mathbf{a} - \Gamma \mathbf{S}_2 \mathbf{b})^H (\mathbf{H}_1 \mathbf{H}_1^H + \mathbf{I})^{-1} (\mathbf{y} - \mathbf{S}_1 \mathbf{a} - \Gamma \mathbf{S}_2 \mathbf{b})\}$$

- When the number of the channel taps is large, $\mathbf{H}_1 \mathbf{H}_1^H$ can be approximated by

$$\mathbf{H}_1 \mathbf{H}_1^H \approx \sum_{l=0}^L \sigma_{h,l}^2 \mathbf{I} \quad (8)$$

- Then the ML estimation is

$$\{\hat{\mathbf{a}}, \hat{\mathbf{b}}, \hat{v}\} = \arg \min_{\mathbf{a}, \mathbf{b}, v} \|\mathbf{y} - \mathbf{S}_1 \mathbf{a} - \Gamma \mathbf{S}_2 \mathbf{b}\|^2. \quad (9)$$

Approximated ML Estimation

- Denote $\mathbf{C} = [\mathbf{S}_1, \Gamma\mathbf{S}_2]$ and $\mathbf{d} = [\mathbf{a}^T, \mathbf{b}^T]^T$. As long as $N > 4L + 2$, \mathbf{d} can be estimated as

$$\hat{\mathbf{d}} = (\mathbf{C}^H \mathbf{C})^{-1} \mathbf{C}^H \mathbf{y}. \quad (10)$$

- CFO estimation is

$$\begin{aligned} \hat{v} &= \arg \min_v \|\mathbf{y} - \mathbf{C}\hat{\mathbf{d}}\|^2 \\ &= \arg \max_v \mathbf{y}^H \mathbf{C} (\mathbf{C}^H \mathbf{C})^{-1} \mathbf{C}^H \mathbf{y} \\ &= \arg \max_v g(v). \end{aligned} \quad (11)$$

Cramér-Rao Bound of CFO Estimation of AML

$$\mathbf{F} = \frac{2}{\sum_l \sigma_{h,l}^2 + 1} \begin{bmatrix} F_{11} & \mathbf{r}^T & \mathbf{s}^T \\ \mathbf{r} & \mathbf{K} & \mathbf{V}^T \\ \mathbf{s} & \mathbf{V} & \mathbf{N} \end{bmatrix}, \quad (12)$$

where

$$F_{11} = \mathbf{b}^H \mathbf{S}_2^H \mathbf{D}^2 \mathbf{S}_2 \mathbf{b}, \quad \mathbf{D} = 2\pi T_s \text{diag}\{0, 1, \dots, (N-1)\},$$

$$\mathbf{r} = \begin{bmatrix} -\Im(\mathbf{S}_1^H \mathbf{D} \mathbf{F} \mathbf{S}_2 \mathbf{b}) \\ \Re(\mathbf{S}_1^H \mathbf{D} \mathbf{F} \mathbf{S}_2 \mathbf{b}) \end{bmatrix}, \quad \mathbf{s} = \begin{bmatrix} -\Im(\mathbf{S}_2^H \mathbf{D} \mathbf{S}_2 \mathbf{b}) \\ \Re(\mathbf{S}_2^H \mathbf{D} \mathbf{S}_2 \mathbf{b}) \end{bmatrix},$$

$$\mathbf{K} = \begin{bmatrix} \Re(\mathbf{S}_1^H \mathbf{S}_1) & -\Im(\mathbf{S}_1^H \mathbf{S}_1) \\ \Im(\mathbf{S}_1^H \mathbf{S}_1) & \Re(\mathbf{S}_1^H \mathbf{S}_1) \end{bmatrix}, \quad \mathbf{N} = \begin{bmatrix} \Re(\mathbf{S}_2^H \mathbf{S}_2) & -\Im(\mathbf{S}_2^H \mathbf{S}_2) \\ \Im(\mathbf{S}_2^H \mathbf{S}_2) & \Re(\mathbf{S}_2^H \mathbf{S}_2) \end{bmatrix},$$

$$\mathbf{V} = \begin{bmatrix} \Re(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{S}_1) & -\Im(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{S}_1) \\ \Im(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{S}_1) & \Re(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{S}_1) \end{bmatrix}.$$

$$\text{CRB}_1(v) = \frac{\sum_l \sigma_{h,l}^2 + 1}{2} [F_{11} - \mathbf{t}_1^T \mathbf{Q}_1^{-1} \mathbf{t}_1]^{-1}, \quad (13)$$

where

$$\mathbf{t}_1 = \begin{bmatrix} \mathbf{r} \\ \mathbf{s} \end{bmatrix}, \quad \mathbf{Q}_1 = \begin{bmatrix} \mathbf{K}, \mathbf{V}^T \\ \mathbf{V}, \mathbf{N} \end{bmatrix}.$$

Nulling Based Method

- Left-multiply both sides of (7) with \mathbf{J}^H , we obtain:

$$\mathbf{J}^H \mathbf{y} = \mathbf{0} + \underbrace{\mathbf{J}^H \mathbf{\Gamma} \mathbf{S}_2}_{\mathbf{G}} \mathbf{b} + \mathbf{J}^H (\mathbf{H} \mathbf{n}_r + \mathbf{n}), \quad (14)$$

- The estimation of \mathbf{b} can be immediately found as

$$\hat{\mathbf{b}} = (\mathbf{G}^H \mathbf{G})^{-1} \mathbf{G}^H \mathbf{y}. \quad (15)$$

- CFO is estimated as

$$\hat{v} = \arg \max_v \mathbf{y}^H \mathbf{J} \mathbf{G} (\mathbf{G}^H \mathbf{G})^{-1} \mathbf{G}^H \mathbf{J}^H \mathbf{y} \quad (16)$$

- The least square (LS) estimation of channel \mathbf{a} is obtained from

$$\hat{\mathbf{a}} = (\mathbf{S}_1^H \mathbf{S}_1)^{-1} \mathbf{S}_1^H (\mathbf{y} - \hat{\mathbf{\Gamma}} \mathbf{S}_2 \hat{\mathbf{b}}), \quad (17)$$

where $\hat{\mathbf{\Gamma}} = \text{diag}\{1, e^{j2\pi\hat{v}T_s}, \dots, e^{j2\pi\hat{v}(N-1)T_s}\}$.

CRB of CFO Estimation of the nulling based method

The FIM is calculated as:

$$\mathbf{F} = \frac{2}{\sum_l \sigma_{h,l}^2 + 1} \begin{bmatrix} F'_{11} & \mathbf{t}_2^T \\ \mathbf{t}_2 & \mathbf{Q}_2 \end{bmatrix}, \quad (18)$$

where

$$\begin{aligned} F'_{11} &= \mathbf{b}^H \mathbf{S}_2^H \mathbf{D} \mathbf{\Gamma}^H \mathbf{J} \mathbf{J}^H \mathbf{D} \mathbf{\Gamma} \mathbf{S}_2 \mathbf{b}, \\ \mathbf{t}_2 &= \begin{bmatrix} -\Im(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{J} \mathbf{J}^H \mathbf{D} \mathbf{\Gamma} \mathbf{S}_2 \mathbf{b}) \\ \Re(\mathbf{S}_2^H \mathbf{\Gamma}^H \mathbf{J} \mathbf{J}^H \mathbf{D} \mathbf{\Gamma} \mathbf{S}_2 \mathbf{b}) \end{bmatrix}, \\ \mathbf{Q}_2 &= \begin{bmatrix} \Re(\mathbf{G}^H \mathbf{G}) & -\Im(\mathbf{G}^H \mathbf{G}) \\ \Im(\mathbf{G}^H \mathbf{G}) & \Re(\mathbf{G}^H \mathbf{G}) \end{bmatrix}. \end{aligned}$$

The CRB of frequency offset estimation is:

$$\text{CRB}_2(v) = \frac{\sum_l \sigma_{h,l}^2 + 1}{2} [F'_{11} - \mathbf{t}_2^T \mathbf{Q}_2^{-1} \mathbf{t}_2]^{-1}. \quad (19)$$

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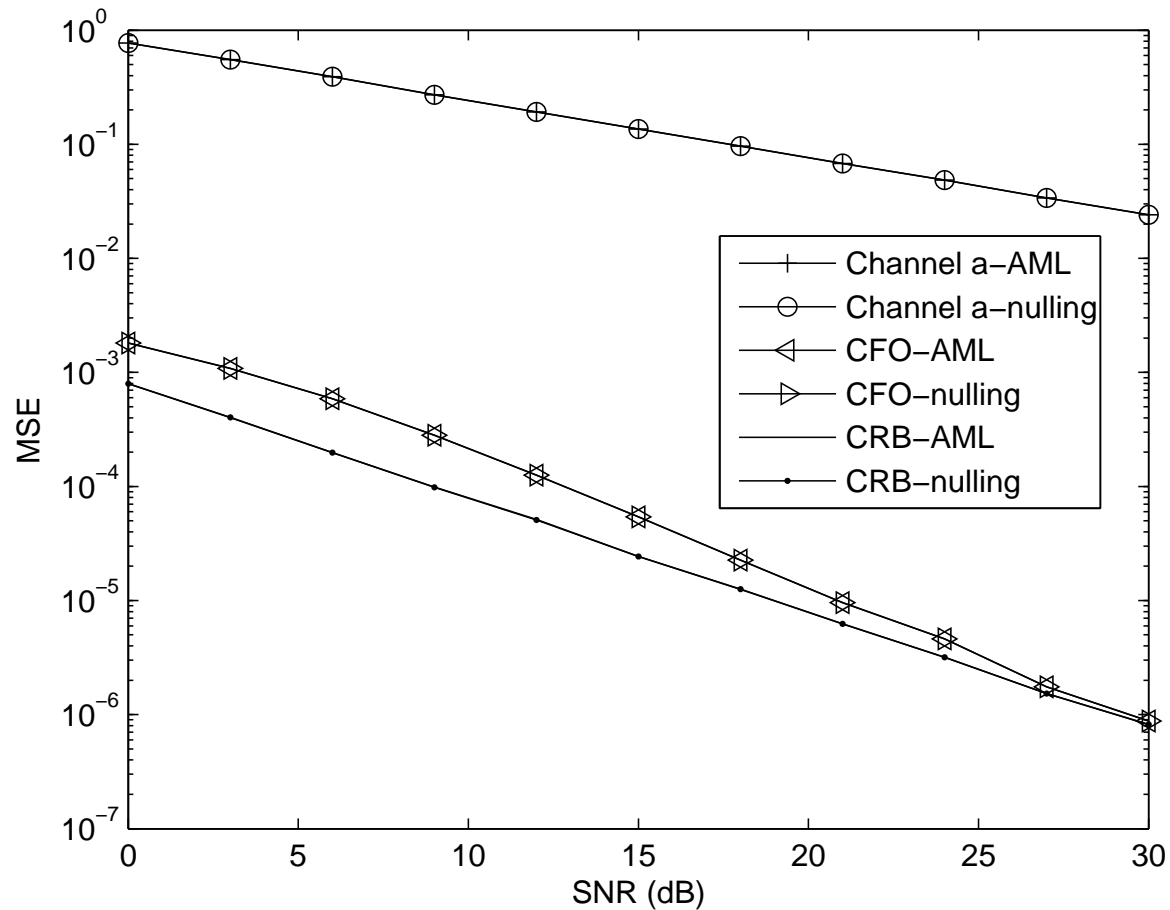


Figure 3: MSEs of CFO and channel estimation versus SNR for AML and nulling based method with orthonormal \mathbf{J}

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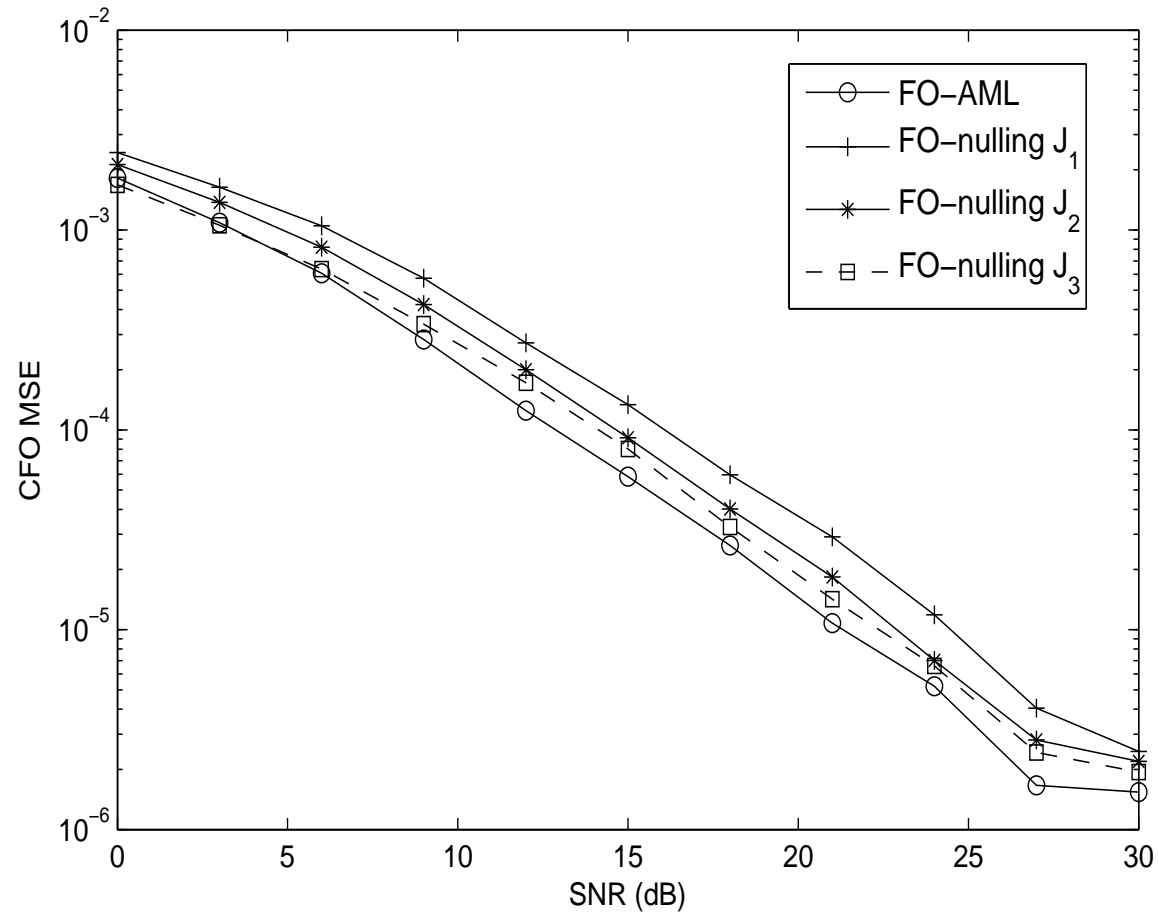


Figure 4: MSEs of CFO estimation versus SNR for AML and nulling based method with random \mathbf{J}

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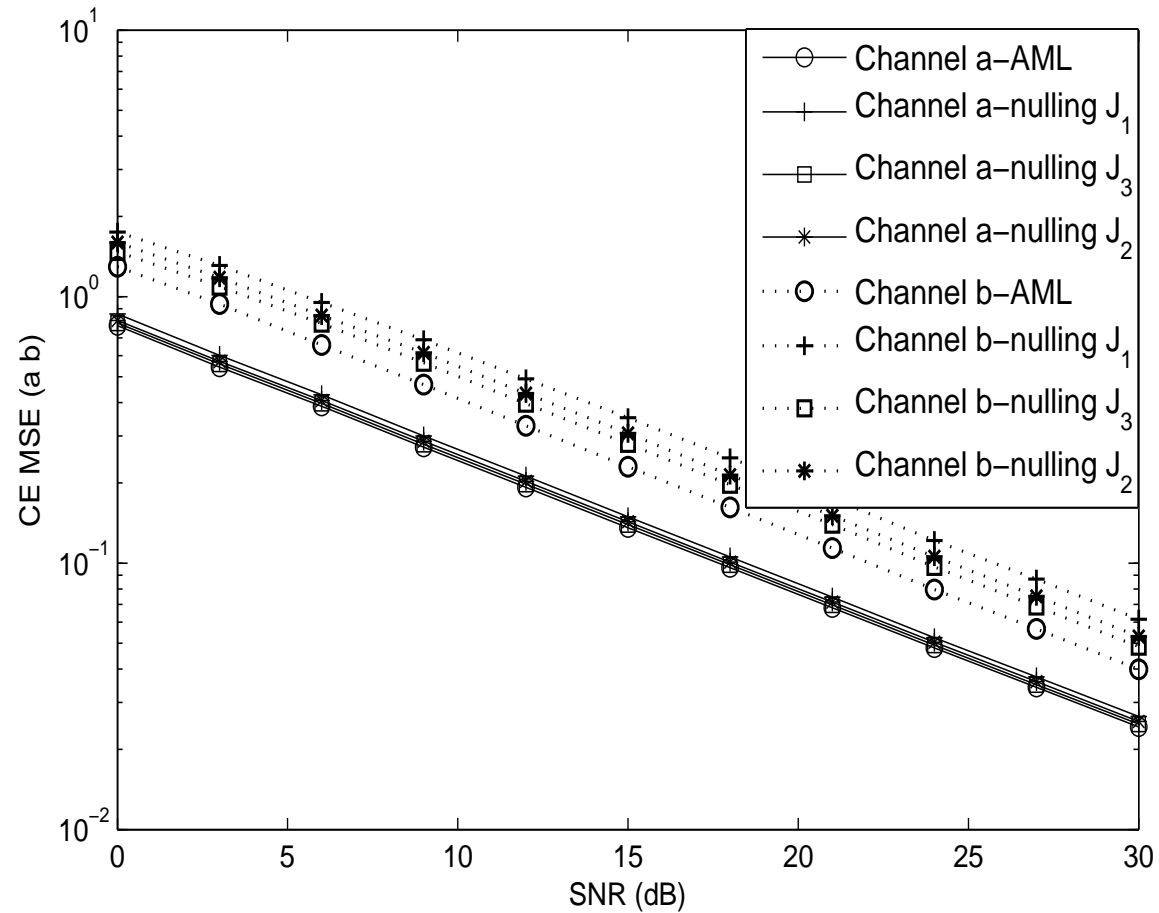


Figure 5: MSEs of channel estimation versus SNR for AML and nulling based method with random J

Conclusions

- Formulate the signal model for two-way relay networks with frequency synchronization errors in a frequency selective environment.
- Develop two joint CFO and channel estimations methods, i.e., AML and nulling-based methods.
- Find CRB of CFO for each method and compare performance of the two methods.
- Here, relay only acts as a repeater. If relay down converts the received signal, the problem will become more complex and interesting.
- Our future work – WCNC and ICC 2010.

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Questions and discussion